

Major product specifications

Driving method	Precision ball screw
Linear motion rolling	Linear Way (ball type)
guide and bearing	Crossed Roller Bearing
Built-in lubrication part	No built-in
Material of table and bed	High carbon steel
Sensor	Provided as standard

Ⅱ-305

Accuracy

	unit: sec
Positioning repeatability	±1
Positioning accuracy	-
Lost motion	-
Parallelism in table motion A	-
Parallelism in table motion B	-
Attitude accuracy	-
Straightness	-
Backlash	-

Points

Rotary positioning table for converting linear motion to rotary motion

This is a positioning table that allows precise angle correction by converting the linear motion to the rotational motion through the rotator mechanism combining the Linear Way and ball screws. High rigidity steel-made table and bed are used and a Crossed Roller Bearing is incorporated in the bearing supporting the table.

Low profile design with high rigidity

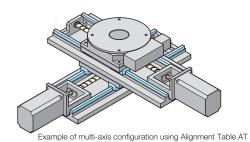
Adoption of Crossed Roller Bearing capable of exerting high rigidity in all direction has achieved low profile, high rigidity, and high precision.

Positioning repeatability of ±1 sec

A rotator for converting linear motion to rotary motion is accurately guided by the combination of Linear Way L and precision ball screw, thus achieving the high positioning repeatability of ±1 sec.

Available as multi-axis configured alignment table

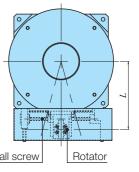
Placing this unit on the slide table of Precision Positioning Table LH enables the configuration of low height XY- θ multi-axis positioning mechanism.



Driving mechanism of Alignment Table AT

Alignment Table AT is driven by stroking a rotator linked to table's outer periphery by driving of ball screw in a linear direction. In order to adjust the distance L and angle from the center of table varied by rotator movement, linear and rotary motion mechanism that follows according to the table angle is incorporated in the rotator. Therefore, in Alignment Table, even when moving the rotator at a same pitch, the table's rotation angle tends to vary depending on the position, so that even when moving it at a constant speed, the rotation speed does not stay constant.





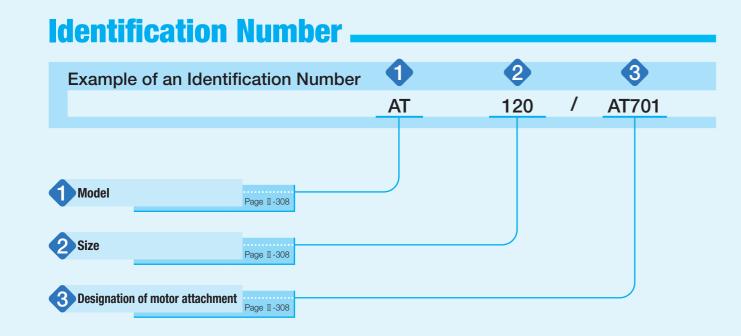
Distance from the center of table ${\it L}$	L unit: mm
Identification number	L
AT120	100
AT200	130
AT300	186

Variation

Shape	Model and size	Table diameter (mm)	Operating angle range (degree)
	AT120	120	_
	AT200	200	± 5
	AT300	300	±10

1N=0.102kgf=0.2248lbs. 1mm=0.03937inch

Ⅱ-306



Identification Number and Specification

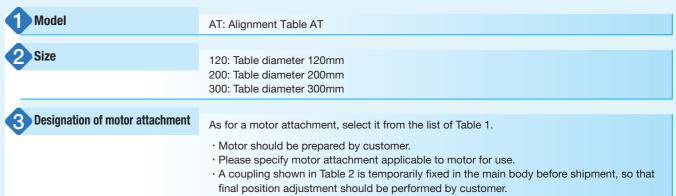


Table 1 Application of motor attachment

	Models of motor to be used		Flange	Motor attachment			
Type	Manufacturer	Series	Model	Rated output W	size mm	AT120 AT200	AT300
	YASKAWA		SGMJV-A5A	- 50		AT701	_
	ELECTRIC	Σ-V	SGMAV-A5A	50	□40	AT701	_
	CORPORATION	Z-V	SGMJV-01A	100	□40	AT701	AT702
			SGMAV-01A	100		AT701	AT702
			HF-MP053, HG-MR053	50		AT701	_
	Mitsubishi Electric	J3, J4	HF-KP053, HG-KR053	30	□40	AT701	_
AC servo	Corporation	00, 04	HF-MP13, HG-MR13	100	⊔ 4 0	AT701	AT702
motor	motor		HF-KP13, HG-KR13	100		AT701	AT702
	Panasonic		MSMD5A	50	□38	AT703	_
		MINAS A5	MSME5A			AT703	_
	Corporation		MSMD01			AT703	AT704
			MSME01	100		AT703	AT704
	Hitachi Industrial Equipment	AD	ADMA-R5L	50	□40	AT701	_
	Systems Co., Ltd	AD	ADMA-01L	100	□40	AT701	AT702
			AR46		□42	AT705	_
			AR66		□60	_	AT706
		α step	AR69		□60	_	AT706
Stepper	ORIENTAL MOTOR		AS46		□42	AT707	_
motor	Co., Ltd.		AS66		□60	_	AT708
			AS69		□60	_	AT708
		RK	RK54 · CRK5	54	□42	AT707	_
		CRK	RK56 · CRK5	6 (1)	□60	_	AT708

Note (1) Applicable to the outer diameter ϕ 8 of motor output shaft.

Remark: For detailed motor specifications, please see respective motor manufacturer's catalog.

Table 2 Coupling models

Table 2 Coupling models			
Motor attachment	Coupling models	Manufacturer	Coupling inertia $J_{\rm c}$ $ imes 10^{-5} { m kg \cdot m^2}$
AT701	MSTS-16-5×8	Nabeya Bi-tech Kaisha	0.084
AT702	UA-25C-8×8	Sakai Manufacturing Co., Ltd	0.290
AT703	MSTS-16-5×8	Nabeya Bi-tech Kaisha	0.084
AT704	UA-25C-8×8	Sakai Manufacturing Co., Ltd	0.290
AT705	MSTS-16-5×6	Nabeya Bi-tech Kaisha	0.084
AT706	MSTS-25C-8×10	Nabeya Bi-tech Kaisha	0.71
AT707	MSTS-16-5×5	Nabeya Bi-tech Kaisha	0.084
AT708	MSTS-25C-8×8	Nabeya Bi-tech Kaisha	0.71

Remark: For detailed coupling specifications, please see respective manufacturer's catalog.

Specifications

Table 3 Specifications of ball screw

unit: mm

Model and size	Shaft dia.	Overall length
AT120	6	103.5
AT200	6	103.5
AT300	10	183

Table 4 Specification

Size	Ball screw lead mm	Rotator resolution μm	Operating angle rance degree	Positioning repeatability sec.	Table inertia J _τ ×10-5kg⋅m²	Starting torque T_s N·m
AT120	1	1 (1)	± 5		0.012	0.03
AT200		1(')	± 5	±1	0.014	0.03
AT300	2	2(1)	±10		0.18	0.04

Note (1) This is a value given when fraction sizes of the motor are 1,000 pulses/rev.

Table 5 Maximum carrying mass

unit: kg

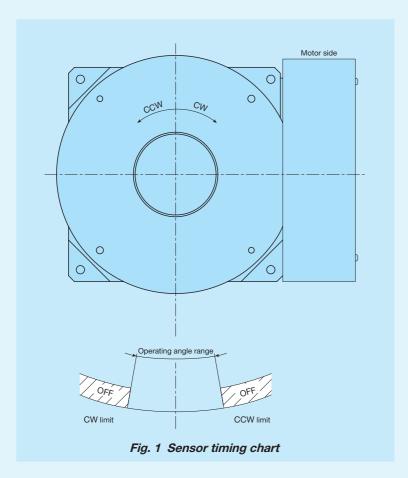
	•
Model and size	Maximum carrying mass
AT120	22
AT200	12
AT300	44

Remark: Applicable in both the horizontal and vertical directions.

Mounting

For the processing accuracy of the Precision Positioning Table mounting surface and the tightening torque of the fixing screws, see page II-29.

Sensor specification



Example of Combination

■ Configuration of XY- θ multi-axis positioning mechanism

Combining the Alignment Table AT with **IKD** precision positioning table of single-axis specification or multi-axis specification enables you to easily configure the XY- θ multi-axis positioning mechanism. Low assembling height, compactness, and high-precision positioning capability enable the table to be used as alignment table for precision measuring equipment, inspection equipment, and assembling device.

Table 6 Configuration example of multi-axis positioning mechanism

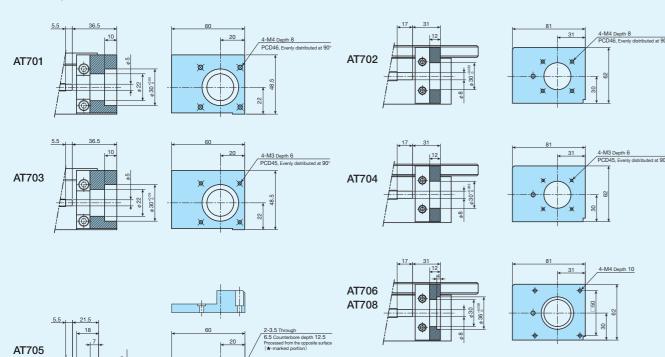
Appearance of multi-axis positioning	Models of IKO pred	cision positio	oning tables	Stroke	length
mechanism	combined with Alignment Table AT			X-axis	Y-axis
		TS125/125	į	50	
		Single-axis	TS125/220	120	
			TS220/220	120	
		specification _	TS220/310	180	
	Precision Positioning Table TS/CT		TS260/350	250	
			CT125/125	50	50
		Two-axis	CT220/220	120	120
		specification	CT260/350	150	250
			CT350/350	250	250
				100, 15	0
			TSLH120M	200	
				250	
				300	
			TSLH220M	150	
		Single-axis specification		200, 25	0, 300
2050				400	
			TSLH320M	300	_
			10211020111	400, 50	0
			T011140014	500	
			TSLH420M	600	
	_			800	400
	Precision Positioning Table		CTLH120M	100	100
	LH			200	100
					200
				300	200 300
				200	200
				300	200
		Two-axis		300	300
		specification		400	300
				400	400
			CTLH320M	300	300
				400	300
				400	400
				500	400
				500	500

Dimensions of Motor Attachment

AT120, AT200

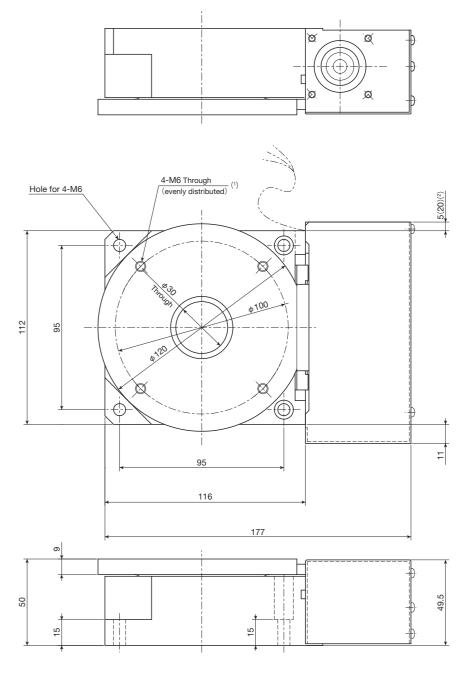
AT707

AT300





AT120



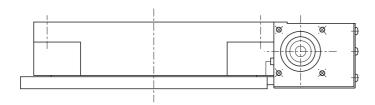
mass: 4.4kg

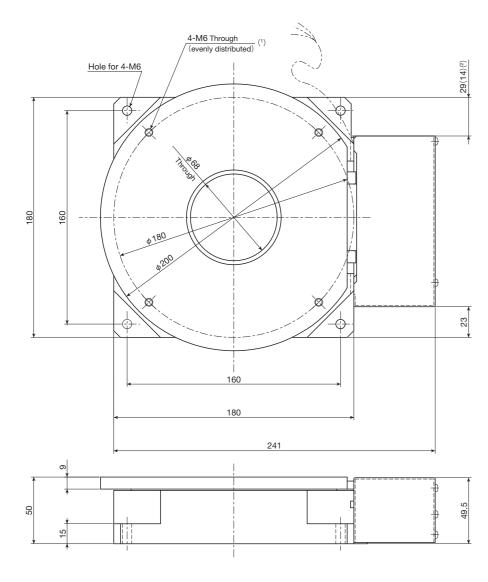
Notes (1) Too deep insertion depth of the mounting bolt may affect the rotation performance of the table, so never insert a bolt longer than the depth of the through hole.

(2) The dimension in () is applicable to AT701 and AT703.

IX Alignment Table AT

AT200

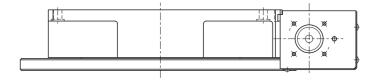


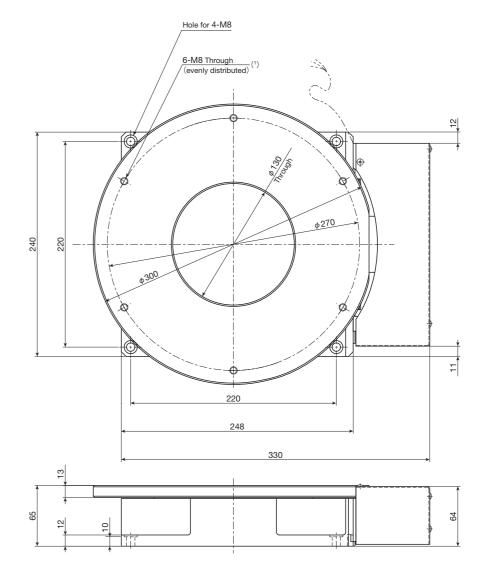


mass: 9.9kg

Notes (1) Too deep insertion depth of the mounting bolt may affect the rotation performance of the table, so never insert a bolt longer than the depth of the through hole.
(2) The dimension in () is applicable to AT701 and AT703.

AT300





mass: 21.0kg

I-314

Note (1) Too deep insertion depth of the mounting bolt may affect the rotation performance of the table, so never insert a bolt longer than the depth of the through hole.